

# Bayesian Modelling of Abundance Data in Ecology Using Joint Species Distribution Models

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## **Context: Joint species distribution models**

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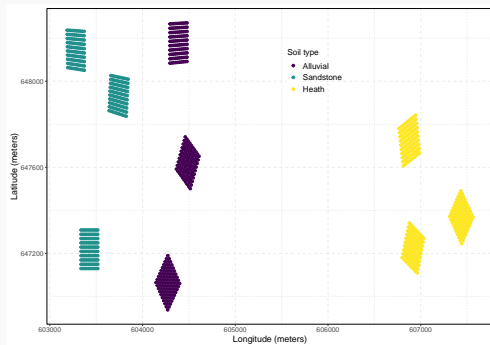
## Ecological context

- **Goal** Describe and understand distribution of species within an ecosystem;
- **Mean** Counting individuals of all encountered species through surveys.

## Statistical challenges

- Multivariate count data;
- Modelling dependencies:
  - Coming from spatial sampling;
  - Coming from species interactions.

Figure 1: Data from Sellan et al. (2019).

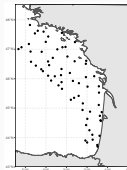


- 900 forest plots (20m × 20m) in Malaysia (Borneo island);
- All trees are counted are counted on all plots: 600 encountered species;

## Ecological question

Do variations in plots communities is explained by the soil composition?

Figure 2: Data from de Outrequin et al. (2025).

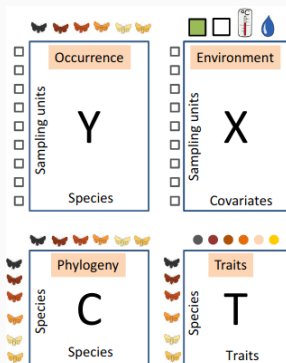


- 64 sites trawling sites across Bay of Biscay (EVOHE Project, 2019);
- Sampling made over different substrats, at different depth;
- 256 invertebrate species encountered.

What are the spatial patterns of species distributions. Are there some communities?

# Joint species distribution data

Figure 3: Source: Ovaskainen and Abrego (2020)



- $\mathbf{Y}$  a  $n \times p$  matrix with entries in  $\mathbb{N}$ ;
- $\mathbf{X}$  a  $n \times n_{\text{cov}}$  matrix of real values;
- $\mathbf{C}$  a  $p \times p$  correlation matrix;
- $\mathbf{T}$  a  $p \times n_{\text{trait}}$  matrix of real values;

## A multivariate generalized linear mixed model approach

- Latent variable approach: modelling of joint distribution of  $(\mathbf{Y}, \mathbf{Z})$ .

For  $1 \leq i \leq n, 1 \leq j \leq p$ ,  $Y_{i,j} | Z_{i,j} \stackrel{\text{ind}}{\sim} \mathcal{D}(\exp(Z_{i,j}), \phi)$ . Observation model

- $\mathcal{D}$  is some distribution (Negative binomial, Poisson) with:
  - Expectation  $\exp(Z_{i,j})$ ;
  - Dispersion parameter  $\phi$ .

$\mathbf{Z} \sim \mathcal{MN}(\mathbf{X}\boldsymbol{\beta}, \Sigma_{\text{Site}}, \Sigma_{\text{Species}})$ . Latent variable

- $\mathcal{MN}(\mathbf{X}\boldsymbol{\beta}, \Sigma_{\text{Site}}, \Sigma_{\text{Species}})$  is the *matrix normal* distribution with:
  - Expectation  $\mathbf{X}\boldsymbol{\beta}$  (a  $n \times p$  matrix);
  - Covariance between rows  $\Sigma_{\text{Site}}$  (a  $n \times n$  symmetric positive definite matrix);
  - Covariance between columns  $\Sigma_{\text{Species}}$  (a  $p \times p$  SPD matrix);
- $\boldsymbol{\beta}$  is an **unknown**  $n_{\text{cov}} \times p$  matrix: **response of species to environment**.

## Definition

$\mathbf{M}$ :  $n \times p$  matrix,  $\mathbf{U}$  (resp.  $\mathbf{V}$ ):  $n \times n$  (resp.  $p \times p$ ) SPD matrix:

$$\mathbf{Z} \sim \mathcal{MN}(\mathbf{M}, \mathbf{U}, \mathbf{V}) \Leftrightarrow \text{vec}(\mathbf{Z}) \sim \mathcal{N}_{np \times np}(\text{vec}(\mathbf{M}), \mathbf{V} \otimes \mathbf{U}).$$

## Properties

- Separability hypothesis over covariances;
- If  $\mathbf{Z} \sim \mathcal{MN}(\mathbf{M}, \mathbf{U}, \mathbf{V})$ , then
$$\mathbf{AZB}^T + \mathbf{C} \sim \mathcal{MN}(\mathbf{AMB}^T + \mathbf{C}, \mathbf{AUA}^T, \mathbf{BVB}^T);$$
  - Useful both for simulation and whitening;

## Modelling the fixed effects

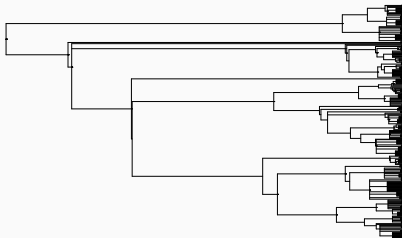
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# Structuring the niches

- Suppose we have access to other data about species:
- Species traits in a matrix  $\mathbf{T}$ :

Species	Growth rate	Wood density	Max. Height
<i>Strychnos borneensis</i>	0.008	0.750	19.749
<i>Dysoxylum indet</i>	0.027	0.585	8.588
<i>Memecylon indet</i>	0.013	0.783	8.692
<i>Cratoxylum cochinchinense</i>	0.025	0.670	9.894
<i>Sterculia stipulata</i>	0.027	0.365	10.087

- Phylogeny, giving a correlation matrix  $\mathbf{C}$ :



## Structuring the $\beta$ matrix

- The matrix  $\beta$  stacks vector of responses to environment:
  - The environmental niches of species;
- Assume that:
  - The **traits** affect  $\beta$  (similar traits lead to similar niche);
  - Columns (species) of  $\beta$  are correlated because of **phylogeny**.

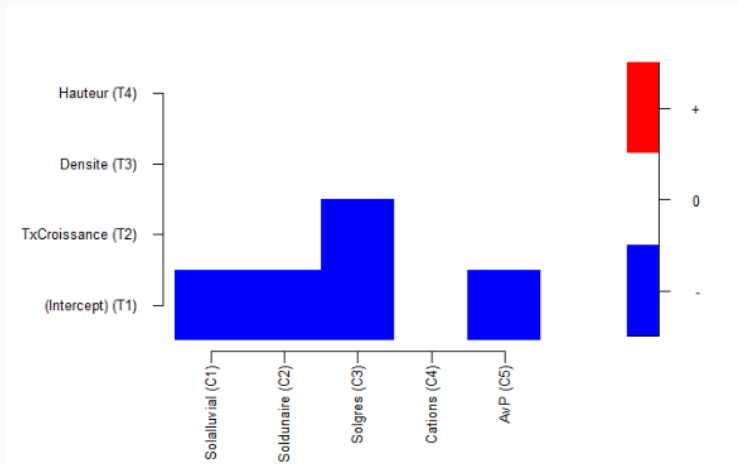
Formally,  $\beta$  is assumed to be a Matrix Normal random variable such that:

$$\beta \sim \mathcal{MN}(\Gamma\mathbf{T}^T, \eta^2\mathbf{I}_{n_{\text{cov}}}, \rho\mathbf{C} + (1 - \rho)\mathbf{I}_p).$$

- $\Gamma$  is a  $n_{\text{cov}} \times n_{\text{trait}}$  matrix structuring  $\beta$ :
  - **Do the species niches are correlated to species traits?**
- $\mathbf{C}$  is the correlation matrix induced by the **phylogeny**;
- $0 \leq \rho \leq 1$  is the weight of **phylogeny** in the columns correlation of  $\beta$ .



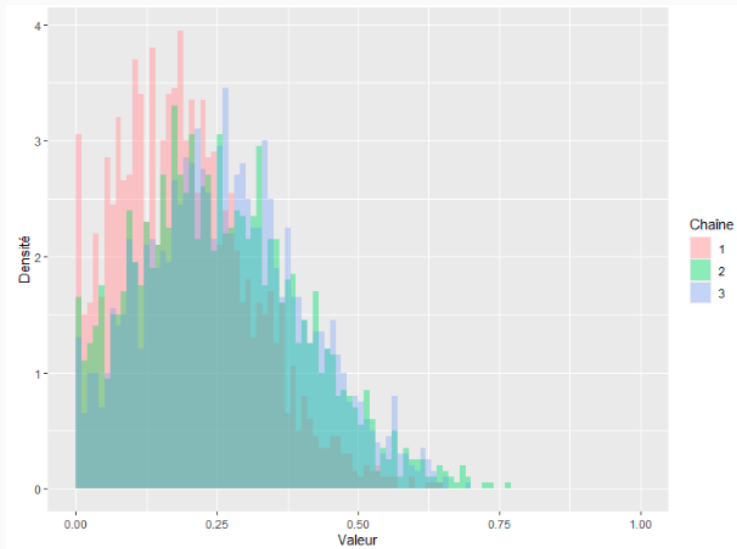
Figure 5: Estimated sign for  $\Gamma$ , obtained with Hmsc package.



- Higher growth rate correlates with low abundance and sandstone soil;

# Influence of phylogeny on niche correlation?

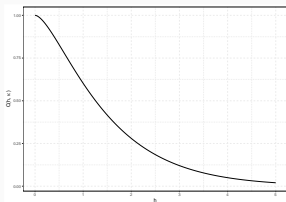
Figure 6: Posterior sampling of weights  $\rho$  of phylogeny.



## Modelling two source of dependences

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Figure 7: Matern covariance function for  $\nu = 1, \sigma^2 = 1, \kappa = 1$



### Model on spatial dependences (rowwise dependences)

- For two sites  $i$  and  $\ell$  separated by a distance  $h_{i,\ell}$ ,  
 $(\Sigma_{\text{Site}})_{i,\ell} = C(h_{i,\ell}, \kappa)$  with:

$$C(h, \kappa) = \kappa h K_1(\kappa h),$$

with  $K_1(\cdot)$  the modified Bessel function of second kind.

- Matern covariance with:
  - Fixed regularity  $\nu = 1$  and marginal variance  $\sigma^2 = 1$ ;
  - Unknown range parameter  $\kappa$  to estimate.

### Model on species dependences (colwise dependences)

- No “natural” structure induced by a “natural” distance;
- Need for a geometrical/statistical structure to avoid  $p \times (p + 1)/2$  free parameters;

### Low rank structures on covariances

- Reducing number of parameters by assuming a low-rank structure

$$\Sigma_{\text{Species}} = \Lambda \Lambda^T,$$

where  $\Lambda$  is a  $p \times q$  matrix with  $q \ll p$ ;

- Probabilistic PCA structure;
- $\Lambda$  interpreted as species response to  $q$  unmeasured covariates;

## Modelling the dependences between species (II)

### Model on species dependences (colwise dependences)

- No “natural” structure induced by a “natural” distance;
- Need for a geometrical/statistical structure to avoid  $p \times (p + 1)/2$  free parameters;

### Model on species dependences (colwise dependences)

- Modelling the precision matrix  $\Omega = \Sigma_{\text{Species}}^{-1}$ ;
- Conditional independence property: For  $1 \leq j, k \leq p$ :

$$\Omega_{j,k} = 0 \Leftrightarrow (\mathbf{Z}_{\cdot,j} | \mathbf{Z}_{\cdot,-(j,k)}) \perp (\mathbf{Z}_{\cdot,k} | \mathbf{Z}_{\cdot,-(j,k)}) .$$

- Induces a graph between species: Draw an edge between species  $j$  and  $k$  iff  $\omega_{j,k} \neq 0$ ;
- *Interpretation*: Ecological interaction network;

$$Y_{i,j} | Z_{i,j} \stackrel{\text{ind}}{\sim} \mathcal{NB}(\exp(Z_{i,j}), \phi),$$
$$\mathbf{Z} \sim \mathcal{MN}(\mathbf{X}\beta, \Sigma(\kappa), \Omega^{-1}).$$

Observation model

Latent variable

## Priors

$$\beta \sim \mathcal{MN}(0, \mathbf{I}_{n_{\text{cov}}}, \mathbf{I}_p)$$

$$\phi \sim \log \mathcal{N}(m, s^2)$$

$$\kappa \sim \mathcal{Gamma}(a, b)$$

$$\Omega \sim \text{Continuous spike and slab prior (CSS)}$$

- CSS comes from Wang (2015).

## Bayesian priors for precision matrices

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### Learning $\Omega$

- We want to learn an interpretable graph;
- This suggest to have a sparse  $\Omega$ ;
- Natural approach: Penalizing matrices having few zeros.

- Let rows of  $\mathbf{Z}$  be centered and independent *i.e.*

$$\mathbf{Z} \sim \mathcal{MN}(0, \mathbf{I}_n, \Omega^{-1}).$$

- The graphical Lasso learns  $\Omega$  by maximizing:

$$\log(\det(\Omega)) - \text{Tr}\left(\frac{1}{n}\mathbf{Z}^T\mathbf{Z}\Omega\right) - \lambda\|\Omega\|_1, \quad \|\Omega\|_1 = \sum_{1 \leq i, j \leq p} |\omega_{i,j}|.$$

- The  $\lambda$  penalty parameter is chosen using model selection criterion.
- Implemented for JSMD (Chiquet, Mariadassou, and Robin (2021)).

- Prior distribution<sup>1</sup> over  $\Omega$ ;

$$p(\Omega|\lambda) \propto \prod_{i < j} \mathcal{Lap}(w_{i,j}|\lambda) \prod_{i=1}^p \mathcal{E}(w_{i,i}|\lambda) \mathbf{1}_{\mathbb{S}_+}(\Omega).$$

- Leads to a Bayesian posterior proportional to graphical Lasso objective;
- Suitable for efficient Gibbs sampling (Wang (2012)).
- Does not lead to a straightforward rule about what is a “true” 0;

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<sup>1</sup> $\mathcal{Lap}(x|\lambda)$  and  $\mathcal{E}(x|\lambda)$  are the p.d.f. of centered Laplace and exponential distributions with parameter  $\lambda$ ,  $\mathbb{S}_+$  is the set of SPD matrices.

## Continuous spike and slab prior for precision matrix (I)

- Idea: Modelling<sup>2</sup> a 0 and non-0 regime;

$$p(\Omega|\theta) = C(\theta)^{-1} \times \left( \prod_{i < j} (1 - \pi) \mathcal{N}(w_{i,j}|0, v_0^2) + \pi \mathcal{N}(w_{i,j}|0, v_1^2) \right) \times \prod_{i=1}^p \mathcal{E}(w_{i,i}|\lambda) \times \mathbf{1}_{\mathbb{S}_+}(\Omega),$$

where:

- $\pi$  can be interpreted as a *a priori* probability of an edge to exist;
- $v_0^2$  and  $v_1^2$  are *a priori* variances of  $w_{i,j}$  under the 2 regimes ( $v_0^2 \ll v_1^2$ );
- $\theta = \{\pi, v_0^2, v_1^2, \lambda\}$ .

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<sup>2</sup> $C(\cdot)$  is a normalizing constant.

- Hierarchical version: Introduction of a latent binary matrix  $\mathbf{G}$ :

$$p(\mathbf{G}|\theta) \propto \mathbf{C}(\mathbf{G}, \theta) \times \prod_{i < j} \pi^{\mathbf{G}_{i,j}} (1 - \pi)^{1 - \mathbf{G}_{i,j}},$$
$$p(\Omega|\theta, \mathbf{G}) = \mathbf{C}(\mathbf{G}, \theta)^{-1} \times \left( \prod_{i < j} \mathcal{N}(w_{i,j} | 0, v_{\mathbf{G}_{i,j}}^2) \times \prod_{i=1}^p \mathcal{E}(w_{i,i} | \lambda) \right) \times \mathbf{1}_{\mathbb{S}_+}(\Omega).$$

- $\mathbf{C}(\mathbf{G}, \theta)$  is an intractable normalizing term that cancels out in the joint distribution of  $(\Omega, \mathbf{G})$ ;
- “The latent binary variables  $\mathbf{G}$  can be viewed as edge-inclusion indicators” (Wang (2015)).

- Lots of methods:
  - Horseshoe prior (Li, Craig, and Bhadra (2019));
  - G-Wishart (Atay-Kayis and Massam (2005));
  - Sparsifying from the Cholesky decomposition (Mastrantonio, Di Loro, and Mingione (2025));
- Nice review with empirical comparisons (Vogels et al. (2024));
- Main challenges: interpretable prior with scalable posterior sampling.

## Posterior sampling

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### Model's equations

$$Y_{i,j}|Z_{i,j} \stackrel{\text{ind}}{\sim} \mathcal{NB}(\exp(Z_{i,j}), \phi),$$

$$\mathbf{Z} \sim \mathcal{MN}(\mathbf{X}\boldsymbol{\beta}, \Sigma(\kappa), \Omega^{-1}),$$

$$\boldsymbol{\beta} \sim \mathcal{MN}(0, \mathbf{I}_{n_{\text{cov}}}, \mathbf{I}_p),$$

$$\phi \sim \log \mathcal{N}(m, s^2),$$

$$\kappa \sim \mathcal{Gamma}(a, b),$$

$$p(\Omega|\theta, \mathbf{G}) = \mathcal{C}(\mathbf{G}, \theta)^{-1} \left( \prod_{i < j} \mathcal{N}(w_{i,j}|0, v_{\mathbf{G}_{i,j}}^2) \times \prod_{i=1}^p \mathcal{E}(w_{i,i}|\lambda) \right) \mathbf{1}_{\mathbb{S}_+}(\Omega),$$

$$p(\mathbf{G}|\theta) \propto \mathcal{C}(\mathbf{G}, \theta) \times \prod_{i \leq j} \pi^{\mathbf{G}_{i,j}} (1 - \pi)^{\mathbf{G}_{i,j}}$$

$p(\mathbf{Z}, \boldsymbol{\beta}, \phi, \kappa, \Omega, \mathbf{G}|\mathbf{Y})$  Target posterior distribution

**Table 2:** Steps of the Gibbs algorithm

<b>Conditional variable</b>	<b>Sampling Method</b>
$\mathbf{Z} \mathbf{Y}, \beta, \kappa, \Omega$	MALA (rowwise)
$\beta \mathbf{Z}, \kappa, \Omega$	Exact (gaussian)
$\phi \mathbf{Y}, \mathbf{Z}$	MALA
$\Omega \mathbf{Z}, \mathbf{G}, \beta, \kappa$	Exact
$\mathbf{G} \Omega$	Exact
$\kappa \mathbf{Z}, \beta, \Omega$	MALA

- *Row whitening*: Compute  $\tilde{\mathbf{Z}} = \mathbf{L}_\kappa^{-1}(\mathbf{Z} - \beta)$ , where  $\mathbf{L}_\kappa \mathbf{L}_\kappa^\top = \Sigma(\kappa)$ ;
- Consider  $\mathbf{S} = \tilde{\mathbf{Z}}^\top \tilde{\mathbf{Z}}$ ;
- Sample new columns of  $\Omega$  iteratively:
- To sample from the (say) last column conditionally to the  $(p - 1)$  other, partition:

$$\mathbf{S} = \begin{pmatrix} \mathbf{S}_{-p,-p} & \vec{s}_{-p,p} \\ \vec{s}_{-p,p}^\top & s_{p,p} \end{pmatrix}$$

- Set:

$$\Omega_{\text{new}} = \begin{pmatrix} \Omega_{-p,-p} & \vec{u} \\ \vec{u}^\top & v + \vec{u}^\top \Omega_{-p,-p} \vec{u} \end{pmatrix},$$

where

$$v \sim \text{Gamma}\left(\frac{n}{2} + 1, \frac{s_{p,p} + \lambda}{2}\right),$$

$$\vec{u} \sim \mathcal{N}_{p-1}(-\mathbf{H}\vec{s}_{-p,p}, \mathbf{H}),$$

where  $\mathbf{H}$  is a matrix depending on  $\mathbf{G}$  (easy to compute).

- Starting from a SPD matrix, it returns a SPD matrix.

- Using the proposed hierarchical prior, conditional of  $\mathbf{G}|\Omega$  sampling is straightforward.
- Sample independently for  $1 \leq i < j \leq p$ :

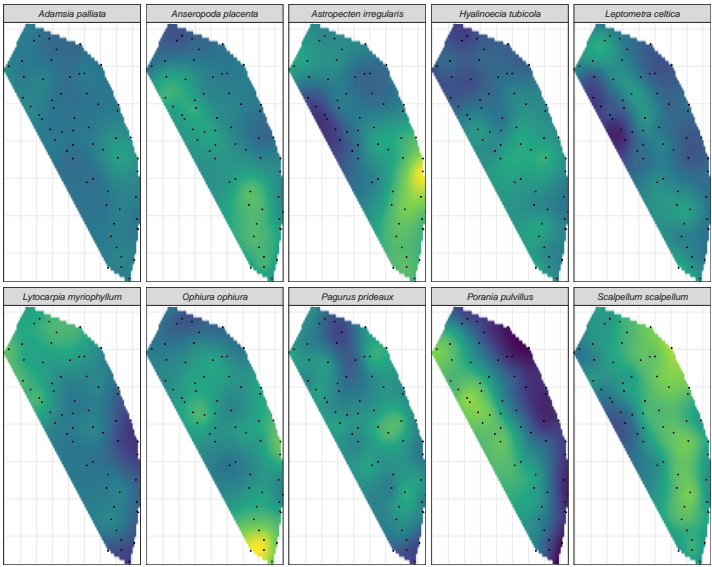
$$\mathbb{P}(\mathbf{G}_{i,j} = 1|\Omega) = \frac{\mathcal{N}(\omega_{i,j}|0, v_1^2)\pi}{\mathcal{N}(\omega_{i,j}|0, v_1^2)\pi + \mathcal{N}(\omega_{i,j}|0, v_0^2)(1 - \pi)} \cdot$$

## **Application to Bay of Biscay invertebrates**

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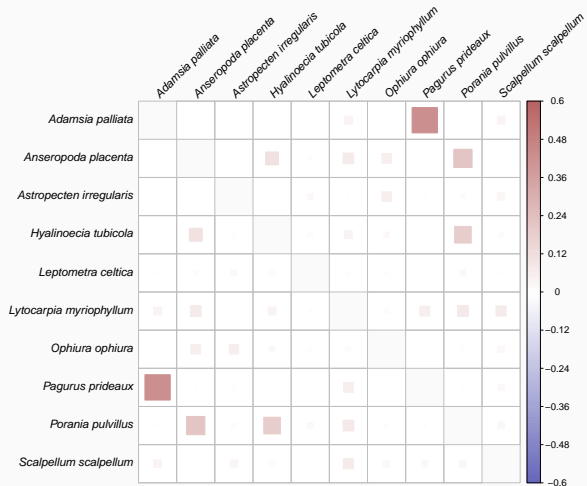
# Estimation of the spatial field per species

Figure 8: Estimated spatial field for 10 species (posterior mean)

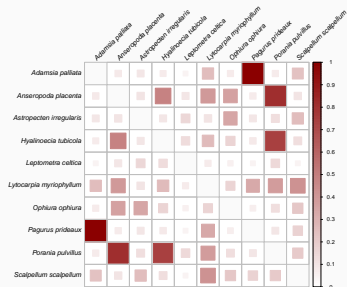


# Estimation of the interaction network (partial correlation)

Figure 9: Estimated partial correlation matrix between species (posterior mean)



**Figure 10:** Posterior prob. of  $G_{i,j} = 1$



**Figure 11:** Number of edges depending on post. prob. threshold.

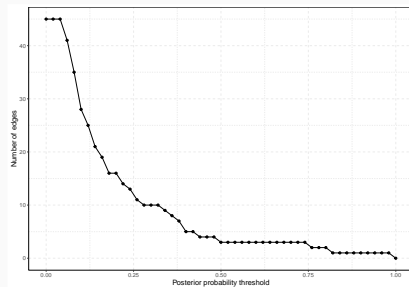
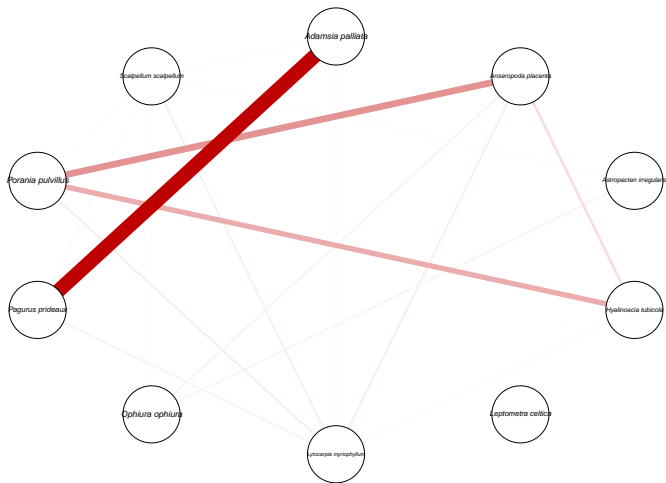


Figure 12: Estimated interaction network



Meet *Pagurus prideaux* and *Adamsa palliata*

Figure 13: Photo from Jim Greenfield flickr.com



## Conclusions

- JSDM gathers classical statistical methods to analyze complex relations.
- Inference is a challenge, leading to various algorithms;
- Possibility of Exact Bayesian inference for network estimation using spatialized data;
- Estimation of two sources of dependence on a separable context;
- Works on  $n$  around hundreds, and  $p$  around dozens;
- For higher scalability (in  $n$  and  $p$ ):
  - Need of appropriate sampler to not depend on Choleski decomposition;
  - Possibility to use approximate methods;

## Perspectives

- Assess ecological pertinence on various different ecological data (trees, mosquitoes, invertebrate, fishes);
  - What are we looking at?
- Proposing some priors based on ecological assumptions;

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